Fig. 1

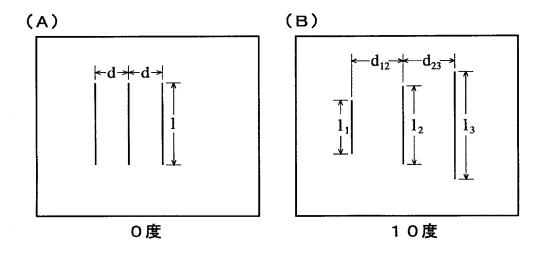
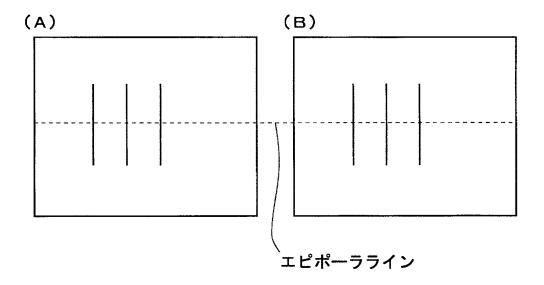
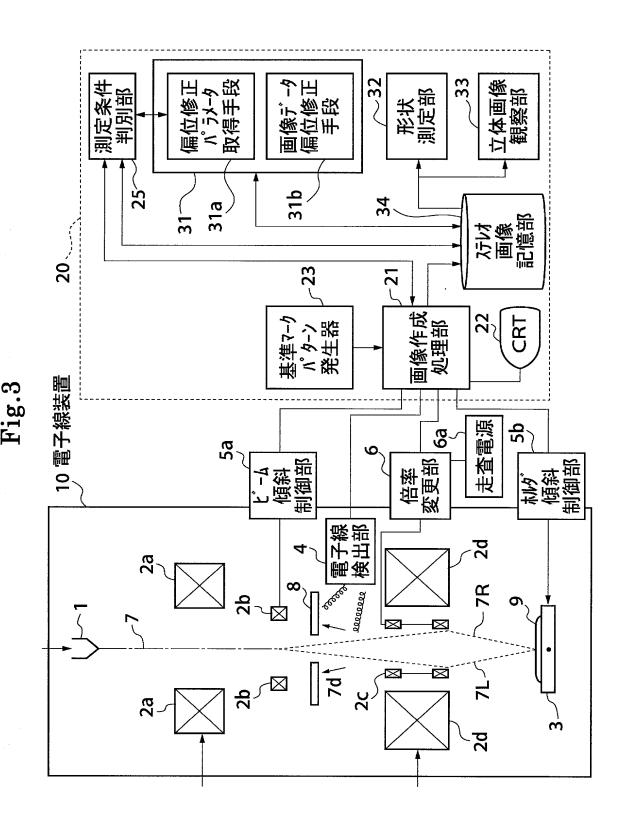


Fig. 2





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Fig. 4

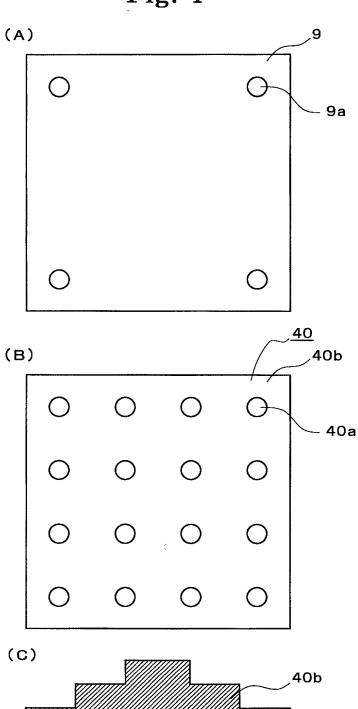


Fig. 5

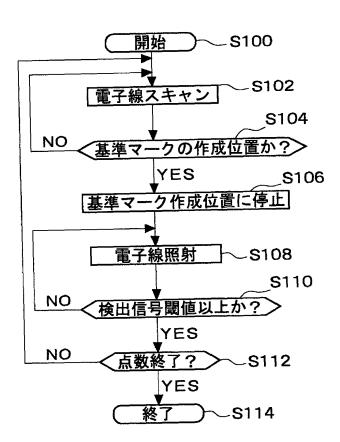


Fig. 6

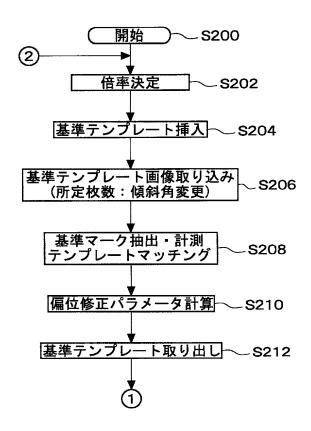


Fig. 7

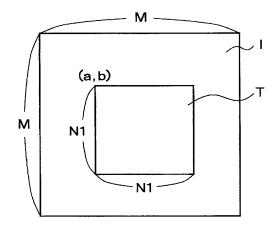
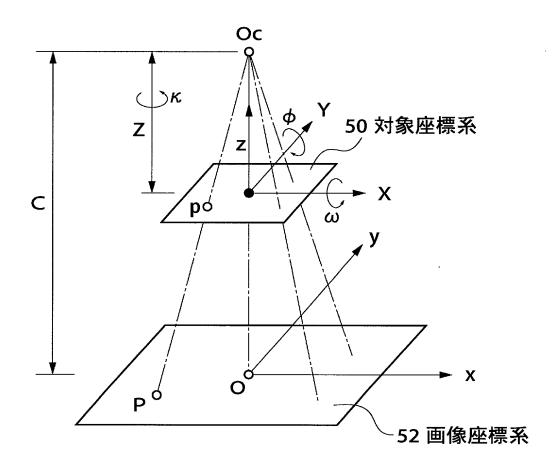


Fig. 8



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Fig. 9

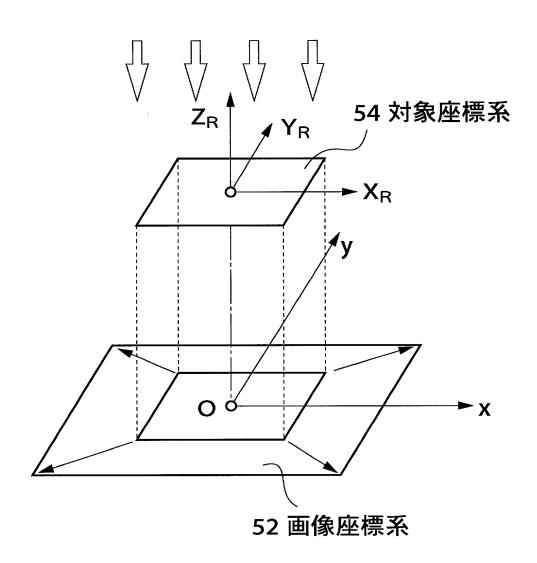


Fig. 10

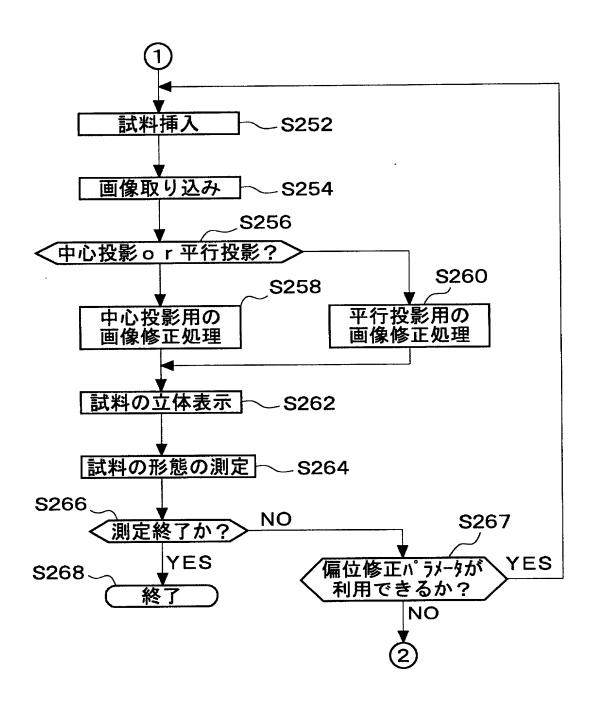


Fig. 11

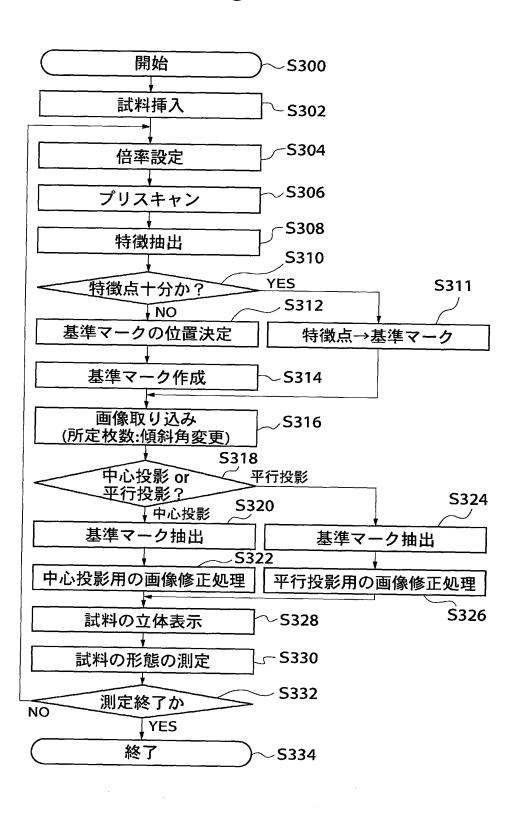


Fig. 12

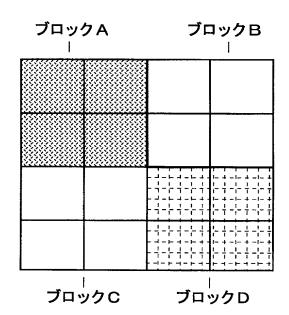
(A) ラプラシアンオペレータ

0	— 1	0
- 1	5	— 1
0	— 1	0

(B)線検出が゚レータ

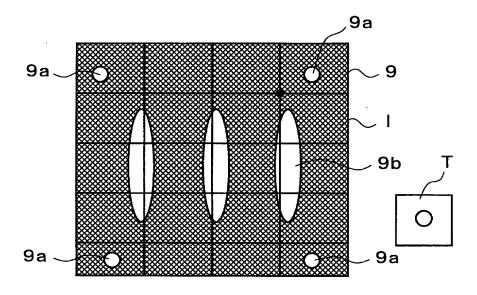
-1/2	1	-1/2
-1/2	1	-1/2
-1/2	1	-1/2

Fig. 13



11/13

Fig. 14



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パラケタ 取得手段 画像データ 偏位修正 手段 \sim 32 立体画像 測定条件 形状 測定部 観察部 判別部 偏位修] 31b 25 31a 34 がな 画像 記憶部 20 画像作成 処理部 パ ターン 発生器 基準7-7 CRI 10 電子線装置 電源 **5**b 6a がが 傾斜 1御部 **走** 倍率 変更部 電子線檢出部 \boxtimes **2**d

